

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2 + \frac{1}{2} m_3 \dot{x}_3^2 \quad \leftarrow (0.5)$$

$$(0.5) V = \frac{1}{2} k (x_2 - x_1)^2 + \frac{1}{2} (3k) (x_3 - x_1)^2 + \frac{1}{2} k x_3^2 \quad \leftarrow (0.5)$$

$$L = T - V$$

eqns de Lagrange: $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}_i} \right) - \frac{\partial L}{\partial x_i} = 0 \quad \leftarrow (0.5)$

$$0.5 \quad m_1 \ddot{x}_1 - k(x_2 - x_1) - (3k)(x_3 - x_1) = F_1 \quad (0.5)$$

$$0.5 \quad m_2 \ddot{x}_2 + k(x_2 - x_1) = F_2 \quad (0.5)$$

$$0.5 \quad m_3 \ddot{x}_3 + (3k)(x_3 - x_1) + kx_3 = F_3 \quad (0.1) \quad \cancel{\text{[scribble]}} \quad (3)$$

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$$T = \frac{1}{2} M \dot{x}^2 + \frac{1}{2} J \dot{\theta}^2$$

$$J = \frac{1}{2} M R^2$$

$$= \frac{1}{2} M \dot{x}^2 + \frac{1}{4} M R^2 \dot{\theta}^2$$

cond. de roulement sans glissement:

$$x = R\theta, \quad \dot{x} = R\dot{\theta}$$

$$= \frac{1}{2} M \dot{x}^2 + \frac{1}{4} M \dot{x}^2$$

$$= \frac{1}{2} \left(\frac{3}{2} M \right) \dot{x}^2$$

(1)

$$V = 2 \cdot \frac{1}{2} k d^2, \quad d = a \sin \theta \approx a \theta$$

$$= \frac{1}{2} (2k) \frac{a^2}{R^2} x^2$$

$$D = \frac{1}{2} c \dot{x}^2$$

$$L = T - V, \text{ eqn:}$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) - \frac{\partial L}{\partial x} + \frac{\partial D}{\partial \dot{x}} = 0 \quad (0.5)$$

$$b) \quad \frac{3}{2} M \ddot{x} + (2k) \frac{a^2}{R^2} x + c \dot{x} = 0$$

$$\ddot{x} + \frac{2c}{3M} \dot{x} + \frac{4k}{3M} \frac{a^2}{R^2} x = 0 \quad (1)$$

$$c) \text{ on a donc: } \omega_0^2 = \frac{4k}{3M} \frac{a^2}{R^2}$$

$$\omega_0 = \frac{a}{R} \sqrt{\frac{4k}{3M}} \quad (0.5)$$

$$\text{et } 2\eta\omega_0 = \frac{2c}{3M}$$

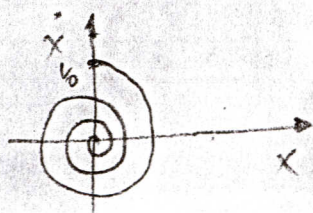
$$\eta = \frac{c}{3M} \cdot \frac{R}{a} \sqrt{\frac{3M}{4k}} \quad (0.5)$$

$$= \frac{R}{2a} \frac{c}{\sqrt{3kM}}$$

d) point critique pour $\eta = 1$ donc

$$a_c = \frac{R}{2} \frac{c}{\sqrt{3kM}} \quad \text{ou} \quad a_c = \frac{c}{3M} \frac{1}{\omega_0} \quad (1)$$

e) pour $a > a_c$, on a $\eta < 1$, donc sous-critique



(0.5)

$$T = \frac{1}{2} M \dot{x}_1^2 + \frac{1}{2} m \dot{x}_2^2$$

(0.5)

$$V = \frac{1}{2} k x_1^2 + \frac{1}{2} k (x_2 - x_1)^2$$

(0.5)

$$L = T - V$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}_i} \right) - \frac{\partial L}{\partial x_i} = 0, \quad i=1,2$$

$$\begin{cases} M \ddot{x}_1 + k x_1 - k (x_2 - x_1) = F \\ m \ddot{x}_2 + k (x_2 - x_1) = 0 \end{cases}$$

(0.5)

$$\begin{cases} \ddot{x}_1 + \frac{2k}{M} x_1 - \frac{k}{m} x_2 = F \\ \ddot{x}_2 + \frac{k}{m} x_2 - \frac{k}{M} x_1 = 0 \end{cases} = \begin{cases} \ddot{x}_1 + \omega_1^2 x_1 - \frac{k}{M} x_2 = F \\ \ddot{x}_2 + \omega_2^2 x_2 - \frac{k}{m} x_1 = 0 \end{cases}$$

b) $F=0$, $x_1 = X_1 e^{i\omega t}$, $x_2 = X_2 e^{i\omega t}$

$$\begin{pmatrix} \omega_1^2 - \omega^2 & -\frac{k}{M} \\ -\frac{k}{m} & \omega_2^2 - \omega^2 \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} = 0$$

(0.5)

$$\det = 0$$

$$(\omega_1^2 - \omega^2)(\omega_2^2 - \omega^2) - \frac{k^2}{mM} = 0$$

$$\omega^4 - (\omega_1^2 + \omega_2^2)\omega^2 + \omega_1^2 \omega_2^2 - \frac{k^2}{mM} = 0$$

$$\text{avec: } \omega_1^2 \omega_2^2 = \frac{2k^2}{mM}$$

$$\omega^4 - (\omega_1^2 + \omega_2^2)\omega^2 + \frac{1}{2}\omega_1^2 \omega_2^2 = 0$$

$$\omega' = \frac{1}{2} \left(\omega_1^2 + \omega_2^2 + \sqrt{4\omega^4 + \omega_1^2 \omega_2^2} \right)$$

$$\omega'' = \frac{1}{2} \left(\omega_1^2 + \omega_2^2 - \sqrt{4\omega^4 + \omega_1^2 \omega_2^2} \right)$$

(1)

$$d) \text{ I. } (\omega_1^2 - \Omega^2) \bar{X}_1 - \frac{k}{M} \bar{X}_2 = \frac{F_0}{M}$$

$$\text{II. } (\omega_2^2 - \Omega^2) \bar{X}_2 - \frac{k}{m} \bar{X}_1 = 0$$

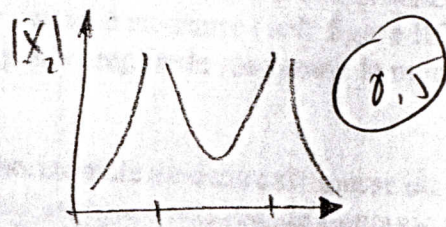
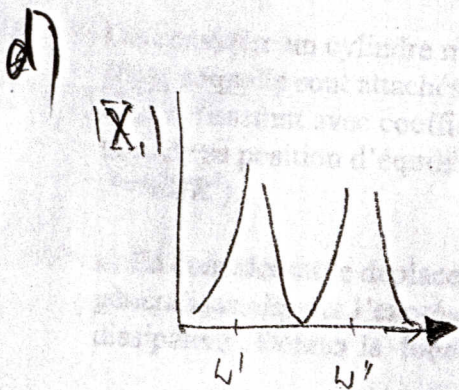
à partir de II. : $\bar{X}_1 = \frac{m}{k} (\omega_2^2 - \Omega^2) \bar{X}_2$, dans I.

$$\left[\frac{m}{k} (\omega_1^2 - \Omega^2) (\omega_2^2 - \Omega^2) - \frac{k}{M} \right] \bar{X}_2 = \frac{F_0}{M}$$

$$\left[(\omega_1^2 - \Omega^2) (\omega_2^2 - \Omega^2) - \frac{k^2}{mM} \right] \bar{X}_2 = \frac{k F_0}{mM}$$

$$\text{(0,5)} \quad \bar{X}_2 = \frac{k}{mM} \frac{F_0}{\left[(\omega_1^2 - \Omega^2) (\omega_2^2 - \Omega^2) - \frac{k^2}{mM} \right]}$$

$$\text{(0,5)} \quad \bar{X}_1 = \frac{F_0}{M} \frac{(\omega_2^2 - \Omega^2)}{\left[(\omega_1^2 - \Omega^2) (\omega_2^2 - \Omega^2) - \frac{k^2}{mM} \right]}$$



pour $\Omega = \omega_1, \omega_2$ $|X_1| \rightarrow \infty$ résonance (0,5)
 $|X_2| \rightarrow \infty$

pour $\Omega = \omega_2$ $|X_1| = 0$ anti-résonance (0,5)
 $|X_2| = \left| \frac{F_0}{M} \right|$

m bouge de tel façon d'exercer une force sur M qui contrebalance la force externe (0,5)