

## Oscillateur harmonique anisotrope à trois dimensions

1) Séparation des variables  $\Rightarrow$  trois équations  $\hat{H} = \hat{H}_x + \hat{H}_y + \hat{H}_z$

$$\hat{H}_x = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + \frac{m\omega^2}{2} \left(1 + \frac{2d}{3}\right) x^2 ; \hat{H}_x \psi(x) = E_x \psi(x)$$

$$\hat{H}_y = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial y^2} + \frac{m\omega^2}{2} \left(1 + \frac{2d}{3}\right) y^2 ; \hat{H}_y \psi(y) = E_y \psi(y)$$

$$\hat{H}_z = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial z^2} + \frac{m\omega^2}{2} \left(1 - \frac{4d}{3}\right) z^2 ; \hat{H}_z \psi(z) = E_z \psi(z)$$

$$\psi(\vec{r}) = \psi(x)\psi(y)\psi(z)$$

2)  $-\frac{\hbar^2}{2m} \frac{\partial^2 \psi(x)}{\partial x^2} + \frac{m\omega^2}{2} \left(1 + \frac{2d}{3}\right) x^2 \psi(x) = E_x \psi(x)$  avec  $\psi(x) = k e^{-\lambda x^2} (m_x=0)$

$$\Rightarrow \frac{\partial^2 \psi(x)}{\partial x^2} = (4\lambda^2 x^2 - 2\lambda) \psi(x)$$

$$-\frac{\hbar^2}{2m} (4\lambda^2 x^2 - 2\lambda) \psi(x) + \frac{m\omega^2}{2} \left(1 + \frac{2d}{3}\right) x^2 \psi(x) = E_x \psi(x)$$

$$\frac{\hbar^2 \lambda}{m} = E_x \text{ avec } \lambda \text{ tel que } -\frac{2\hbar^2 \lambda^2}{m} + \frac{m\omega^2}{2} \left(1 + \frac{2d}{3}\right) = 0$$

annulation du terme en  $x^2$ !

$$\Leftrightarrow E_x = \frac{\hbar^2 \lambda^2}{m^2} \quad \Leftrightarrow \lambda^2 = \frac{m^2 \omega^2 \left(1 + \frac{2d}{3}\right)}{4\hbar^2}$$

soit  $E_x = \frac{\hbar^2 \omega^2}{4} \left(1 + \frac{2d}{3}\right) \Rightarrow E_x = \frac{\hbar \omega}{2} \sqrt{1 + \frac{2d}{3}}$

- Calcul identique pour l'oscillateur selon  $oy \Rightarrow E_y = \frac{\hbar \omega}{2} \sqrt{1 + \frac{2d}{3}} (m_y=0)$
- Même principe selon  $oz \Rightarrow E_z = \frac{\hbar \omega}{2} \sqrt{1 - \frac{4d}{3}} (m_z=0)$

$\Rightarrow$  En conclusion

$$\left\{ \begin{array}{l} \omega_x = \omega \sqrt{1 + \frac{2d}{3}} = \omega_y ; \omega_z = \omega \sqrt{1 - \frac{4d}{3}} \\ \alpha = \frac{1}{2} + \frac{1}{2} \quad \left(\frac{1}{2} \text{ quantum par degré de liberté}\right) \\ \gamma = \frac{1}{2} \\ + \beta = \frac{1}{2} \text{ (racine carrée)} \end{array} \right.$$

Soit  $E(m_x, m_y, m_z) = \frac{\hbar \omega}{2} \left( (m_x + m_y + 1) \sqrt{1 + \frac{2d}{3}} + (m_z + \frac{1}{2}) \sqrt{1 - \frac{4d}{3}} \right) \frac{\hbar \omega}{2}$

3) Energie état fondamental  $d=0 \Rightarrow E = \frac{3}{2} \hbar \omega$

$m_x = m_y = m_z = 0 \quad d = \frac{3}{4} \Rightarrow E = \sqrt{\frac{3}{2}} \hbar \omega$

Variations : décroissante sur l'ensemble de l'intervalle  $d \in [0, \frac{3}{4}]$   
max pour  $d=0$

$$\left. \frac{dE}{dd} \right|_{d=0} = 0 \quad ; \quad \left. \frac{dE}{dd} \right|_{d=3/4} = -\sigma$$

Energie d'interaction

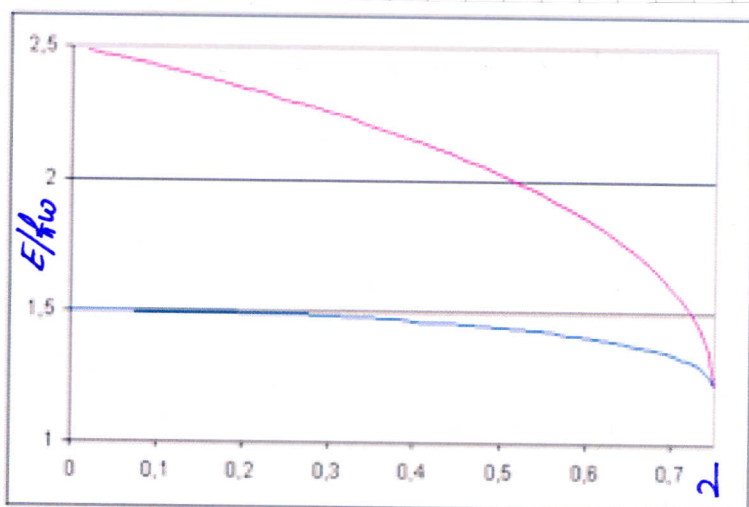
$$d=0 \Rightarrow E = \frac{5}{2} \frac{\hbar \omega}{2}$$

$$m_x = m_y = 0 ; m_z = 1$$

$$d=3/4 \Rightarrow E = \sqrt{\frac{3}{2}} \frac{\hbar \omega}{2} \Rightarrow \text{dégénéré avec le fondamental}$$

Variations:  $\left\{ \begin{array}{l} \text{d'écroissance sur l'ensemble de l'intervalle } d \in [0, 3/4] \\ \text{aucun extremum} \end{array} \right.$

$$\left. \frac{dE}{dd} \right|_{d=0} = -\frac{2}{3} \frac{\hbar \omega}{3} \quad ; \quad \left. \frac{dE}{dd} \right|_{d=3/4} = -\sigma$$



Placement cinétique

$$|+1\rangle, |0\rangle \text{ et } |-1\rangle$$

$$\hat{H}_0 = a \hat{J}_3 + \frac{b}{\hbar} \hat{J}_3^2$$

$$1) \hat{H}_0 |JM\rangle = a \hat{J}_3 |JM\rangle + \frac{b}{\hbar} \hat{J}_3 \hat{J}_3 |JM\rangle = E_0 |JM\rangle$$

$$= a \frac{\hbar}{\hbar} M |JM\rangle + \frac{b}{\hbar} \frac{\hbar^2}{\hbar} M^2 |JM\rangle = E_0 |JM\rangle$$

$$\text{soit } (a \hbar M + b \hbar M^2) = E_0 (M) \Rightarrow E_0(M) = \hbar (b M^2 + a M)$$

polynôme du 2<sup>nd</sup> degré en M

$$|+1\rangle \Rightarrow E_0(+1) = \hbar (a+b)$$

$$|0\rangle \Rightarrow E_0(0) = 0$$

$$|-1\rangle = E_0(-1) = -\hbar (a-b)$$

$\left. \begin{array}{l} \text{deg si } a = \pm b ; a=0 \\ \text{soit } \frac{b}{a} = \pm 1 \end{array} \right\}$

2/  $W = -\vec{M} \cdot \vec{B}_0 = -\gamma \vec{J} \cdot \vec{B}_0 = -\gamma B_0 \hat{J}_u = \omega_0 \hat{J}_u$   
 avec  $\hat{J}_u = \hat{J}_x \sin\Theta \cos\phi + \hat{J}_y \sin\Theta \sin\phi + \hat{J}_z \cos\Theta$

$\hat{J}_x = \frac{\hat{J}_+ + \hat{J}_-}{2}$  et  $\hat{J}_y = \frac{\hat{J}_+ - \hat{J}_-}{2i}$   
 Il faut évaluer

$$\begin{cases} \hat{J}_+ |1\rangle = 0 & \hat{J}_- |1\rangle = \sqrt{2} |0\rangle \\ \hat{J}_+ |0\rangle = \sqrt{2} |1\rangle & \hat{J}_- |0\rangle = \sqrt{2} |-1\rangle \\ \hat{J}_+ |-1\rangle = \sqrt{2} |0\rangle & \hat{J}_- |-1\rangle = 0 \end{cases}$$

Soit 
$$\begin{cases} \hat{J}_x |1\rangle = \frac{\hbar}{\sqrt{2}} |0\rangle \\ \hat{J}_x |0\rangle = \frac{\hbar}{\sqrt{2}} (|1\rangle + |-1\rangle) \\ \hat{J}_x |-1\rangle = \frac{\hbar}{\sqrt{2}} |0\rangle \end{cases} \quad \begin{cases} \hat{J}_y |1\rangle = i \frac{\hbar}{\sqrt{2}} |0\rangle \\ \hat{J}_y |0\rangle = -i \frac{\hbar}{\sqrt{2}} (|1\rangle - |-1\rangle) \\ \hat{J}_y |-1\rangle = -i \frac{\hbar}{\sqrt{2}} |0\rangle \end{cases}$$

et 
$$\begin{cases} \hat{J}_z |1\rangle = \hbar |1\rangle \\ \hat{J}_z |0\rangle = 0 \\ \hat{J}_z |-1\rangle = -\hbar |-1\rangle \end{cases}$$

$$\hat{J}_u = \sin\Theta \cos\phi \begin{pmatrix} 0 & \frac{\hbar}{\sqrt{2}} & 0 \\ \frac{\hbar}{\sqrt{2}} & 0 & \frac{\hbar}{\sqrt{2}} \\ 0 & \frac{\hbar}{\sqrt{2}} & 0 \end{pmatrix} + i \sin\Theta \sin\phi \begin{pmatrix} 0 & -\frac{\hbar}{\sqrt{2}} & 0 \\ \frac{\hbar}{\sqrt{2}} & 0 & -\frac{\hbar}{\sqrt{2}} \\ 0 & \frac{\hbar}{\sqrt{2}} & 0 \end{pmatrix} + \cos\Theta \begin{pmatrix} \hbar & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\hbar \end{pmatrix}$$

$$= \begin{pmatrix} \hbar \cos\Theta & \frac{\hbar}{\sqrt{2}} (\sin\Theta \cos\phi - i \sin\Theta \sin\phi) & 0 \\ \frac{\hbar}{\sqrt{2}} (\sin\Theta \cos\phi + i \sin\Theta \sin\phi) & 0 & \frac{\hbar}{\sqrt{2}} (\sin\Theta \cos\phi - i \sin\Theta \sin\phi) \\ 0 & \frac{\hbar}{\sqrt{2}} (\sin\Theta \cos\phi + i \sin\Theta \sin\phi) & -\hbar \cos\Theta \end{pmatrix}$$

soit  $W = \hbar \omega_0 \begin{pmatrix} \cos\Theta & \frac{1}{\sqrt{2}} \sin\Theta e^{-i\phi} & 0 \\ \frac{1}{\sqrt{2}} \sin\Theta e^{i\phi} & 0 & \frac{1}{\sqrt{2}} \sin\Theta e^{-i\phi} \\ 0 & \frac{1}{\sqrt{2}} \sin\Theta e^{i\phi} & -\cos\Theta \end{pmatrix}$  soit  $\alpha = \frac{1}{\sqrt{2}}$

3)  $a = b$   $\vec{u} // \vec{ox}$   $\omega_0 \ll a \rightarrow$  perturbation  $W$   
 $E_0(0) = E_0(-1)$  dégénérescence en  $\hat{H}_0$   $\Theta = \pi/2, \phi = 0$

$$W = \frac{\hbar \omega_0}{2} \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & 0 \end{pmatrix} \begin{matrix} |+\rangle \\ |0\rangle \\ |-1\rangle \end{matrix} = \frac{\hbar \omega_0}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{matrix} |+\rangle \\ |0\rangle \\ |-1\rangle \end{matrix}$$

- Niveau non dégénéré  $|+1\rangle$   $E_{|+1\rangle} = 2\hbar a + 0 = 2\hbar a$
- Niveaux dégénérés en  $\hat{H}_0$  Diagonaliser  $\Pi = \frac{\hbar \omega_0}{\sqrt{2}} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

$\Rightarrow$  2 valeurs propres + 2 vecteurs propres

$$E_+^{(1)} = \frac{\hbar \omega_0}{\sqrt{2}} \Rightarrow |\psi_+\rangle = \frac{1}{\sqrt{2}} (|0\rangle + |-1\rangle)$$

$$E_-^{(1)} = -\frac{\hbar \omega_0}{\sqrt{2}} \Rightarrow |\psi_-\rangle = \frac{1}{\sqrt{2}} (|0\rangle - |-1\rangle)$$

$\rightarrow$  levée de dégénérescence par  $\hat{W}$

4)  $b = 2a$

$$\left. \begin{matrix} E_0(+1) = 3\hbar a = E_{+1} \\ E_0(0) = 0 = E_0 \\ E_0(-1) = \hbar a = E_{-1} \end{matrix} \right\} \Rightarrow \text{plus de dégénérescence}$$

avec  $E_0 - E_{-1} = -\hbar a$  et  $E_0 - E_{+1} = -3\hbar a$

$$W = \frac{\hbar \omega_0}{2} \begin{pmatrix} \cos\Theta & \frac{1}{\sqrt{2}} \sin\Theta e^{-i\phi} & 0 \\ \frac{1}{\sqrt{2}} \sin\Theta e^{i\phi} & 0 & \frac{1}{\sqrt{2}} \sin\Theta e^{-i\phi} \\ 0 & \frac{1}{\sqrt{2}} \sin\Theta e^{i\phi} & -\cos\Theta \end{pmatrix} \begin{matrix} |+\rangle \\ |0\rangle \\ |-1\rangle \end{matrix}$$

Calcul de  $\langle -1|W|0\rangle$  et  $\langle +1|W|0\rangle$

$$\bullet \langle -1|W|0\rangle = \frac{\hbar \omega_0}{\sqrt{2}} \sin\Theta e^{i\phi}$$

$$\bullet \langle +1|W|0\rangle = \frac{\hbar \omega_0}{\sqrt{2}} \sin\Theta e^{-i\phi}$$

$$\Rightarrow |\psi_0\rangle = |0\rangle - \frac{\omega_0 \sin\Theta e^{i\phi}}{a\sqrt{2}} |-1\rangle - \frac{\omega_0 \sin\Theta e^{-i\phi}}{3a\sqrt{2}} |+1\rangle$$

5)  $\triangle M \rightarrow$  calculer  $\langle \psi_0 | \hat{M}_x | \psi_0 \rangle = \gamma \langle \psi_0 | \hat{J}_x | \psi_0 \rangle$   
 $\langle \psi_0 | \hat{M}_y | \psi_0 \rangle = \gamma \langle \psi_0 | \hat{J}_y | \psi_0 \rangle$   
 $\langle \psi_0 | \hat{M}_z | \psi_0 \rangle = \gamma \langle \psi_0 | \hat{J}_z | \psi_0 \rangle$

$$\begin{aligned} \rightarrow \hat{J}_x |\psi_0\rangle &= \hat{J}_x \left( |0\rangle - \frac{\omega_0 \sin\theta e^{i\phi}}{a\sqrt{2}} |-1\rangle - \frac{\omega_0 \sin\theta e^{-i\phi}}{3a\sqrt{2}} |1\rangle \right) \\ &= \frac{\hbar}{\sqrt{2}} (|1\rangle + |-1\rangle) - \frac{\omega_0 \sin\theta e^{i\phi}}{a\sqrt{2}} \frac{\hbar}{\sqrt{2}} |0\rangle - \frac{\omega_0 \sin\theta e^{-i\phi}}{3a\sqrt{2}} \frac{\hbar}{\sqrt{2}} |0\rangle \\ &= \frac{\hbar}{\sqrt{2}} |1\rangle - \frac{\hbar \omega_0 \sin\theta}{2a} \left( e^{i\phi} + e^{-i\phi} \right) |0\rangle + \frac{\hbar}{\sqrt{2}} |-1\rangle \end{aligned}$$

$$\begin{aligned} \text{scal} \langle \hat{J}_x \rangle_{|\psi_0\rangle} &= -\frac{\hbar \omega_0 \sin\theta}{2a} \left( e^{i\phi} + e^{-i\phi} \right) - \frac{\hbar \omega_0 \sin\theta}{2a} e^{-i\phi} - \frac{\hbar \omega_0 \sin\theta e^{i\phi}}{2a \times 3} \\ &= -\frac{3\hbar \omega_0 \sin\theta}{3a} \left( \frac{e^{i\phi} + e^{-i\phi}}{2} \right) - \frac{\hbar \omega_0 \sin\theta}{3a} \left( \frac{e^{i\phi} + e^{-i\phi}}{2} \right) \\ &= -\frac{4\hbar \omega_0 \sin\theta \cos\phi}{3a} \end{aligned}$$

$$\begin{aligned} \rightarrow \hat{J}_y |\psi_0\rangle &= \hat{J}_y \left( |0\rangle - \frac{\omega_0 \sin\theta e^{i\phi}}{a\sqrt{2}} |-1\rangle - \frac{\omega_0 \sin\theta e^{-i\phi}}{3a\sqrt{2}} |1\rangle \right) \\ &= -\frac{i\hbar}{\sqrt{2}} (|1\rangle - |-1\rangle) - \frac{\omega_0 \sin\theta e^{i\phi}}{ia\sqrt{2}} \frac{\hbar}{\sqrt{2}} |0\rangle - \frac{\omega_0 \sin\theta e^{-i\phi}}{3a\sqrt{2}} \frac{i\hbar}{\sqrt{2}} |0\rangle \\ &= -\frac{i\hbar}{\sqrt{2}} |1\rangle - \frac{\hbar \omega_0 \sin\theta}{2ai} \left( e^{i\phi} - e^{-i\phi} \right) |0\rangle + \frac{i\hbar}{\sqrt{2}} |-1\rangle \end{aligned}$$

$$\begin{aligned} \text{scal} \langle \hat{J}_y \rangle_{|\psi_0\rangle} &= -\frac{\hbar \omega_0 \sin\theta}{2ai} \left( e^{i\phi} - e^{-i\phi} \right) + \frac{\hbar \omega_0 \sin\theta e^{-i\phi}}{2ai} - \frac{\hbar \omega_0 \sin\theta e^{i\phi}}{3 \times 2ai} \\ &= -\frac{2\hbar \omega_0 \sin\theta}{3a} \left( \frac{e^{i\phi} - e^{-i\phi}}{2i} \right) - \frac{\hbar \omega_0 \sin\theta}{3a} \left( \frac{e^{i\phi} - e^{-i\phi}}{2i} \right) \\ &= -\frac{4\hbar \omega_0 \sin\theta \sin\phi}{3a} \end{aligned}$$

$$\begin{aligned} \rightarrow \hat{J}_z |\psi_0\rangle &= \hat{J}_z \left( |0\rangle - \frac{\omega_0 \sin\theta e^{i\phi}}{a\sqrt{2}} |-1\rangle - \frac{\omega_0 \sin\theta e^{-i\phi}}{3a\sqrt{2}} |1\rangle \right) \\ &= +\frac{\hbar \omega_0 \sin\theta e^{i\phi}}{a\sqrt{2}} |-1\rangle - \frac{\hbar \omega_0 \sin\theta e^{-i\phi}}{3a\sqrt{2}} |1\rangle \end{aligned}$$

$$\text{scal} \langle \hat{J}_z \rangle_{|\psi_0\rangle} = \frac{0}{3} \frac{\hbar \omega_0^2 \sin^2\theta}{2a^2} + \frac{\hbar \omega_0^2 \sin^2\theta}{2 \times 9a^2} = \frac{-8\hbar \omega_0^2 \sin^2\theta}{18a^2} = 0 \quad \text{ordre 2} \quad \text{ordre 1}$$