

Oscillateur harmonique

PARTIE A] $|\psi(0)\rangle = \sum_m c_m |\varphi_m\rangle$; $H|\varphi_m\rangle = (m + \frac{1}{2})\hbar\omega |\varphi_m\rangle$

1) $H|\psi(t)\rangle = i\hbar \frac{\partial}{\partial t} |\psi(t)\rangle$

$\Rightarrow |\psi(t)\rangle = \sum_m c_m(0) e^{-i(m+\frac{1}{2})\omega t} |\varphi_m\rangle$

2) P : $E \geq \frac{\hbar\omega}{2}$

P_m d'après E_m : $P_m = |\langle \varphi_m | \psi(t) \rangle|^2 = |c_m|^2$

$\begin{cases} E_0 = \frac{\hbar\omega}{2} \\ E_1 = \frac{3\hbar\omega}{2} \\ E_2 = \frac{5\hbar\omega}{2} \end{cases}$

$P = \sum_{m=2}^{\infty} |c_m|^2 = 1 - |c_0|^2 - |c_1|^2$

$P=0 \Rightarrow |c_0|^2 + |c_1|^2 = 1 \Rightarrow c_0$ et c_1 non nuls.

3) $|\psi(0)\rangle = c_0 |\varphi_0\rangle + c_1 |\varphi_1\rangle \Rightarrow$ cd't normalisation $|c_0|^2 + |c_1|^2 = 1$

$\langle H \rangle_{\psi(0)} = P_0 E_0 + P_1 E_1 = |c_0|^2 \frac{\hbar\omega}{2} + |c_1|^2 \frac{3\hbar\omega}{2} = \hbar\omega \left(\frac{1}{2} |c_0|^2 + \frac{3}{2} |c_1|^2 \right)$

$= \frac{\hbar\omega}{2}$

ce qui donne $\begin{cases} |c_0|^2 + |c_1|^2 = 1 & \text{soit } |c_0|^2 = \frac{1}{2} \\ \frac{1}{2} |c_0|^2 + \frac{3}{2} |c_1|^2 = 1 & \text{et } |c_1|^2 = \frac{1}{2} \end{cases}$

4) $c_0 = \frac{1}{\sqrt{2}}$ et $|c_1| = \frac{1}{\sqrt{2}}$ ($c_1 = |c_1| e^{i\theta_1}$)

$\langle H \rangle = \frac{\hbar\omega}{2}$; $\langle X \rangle = \frac{1}{2} \sqrt{\frac{\hbar}{m\omega}}$ avec $X = \sqrt{\frac{\hbar}{2m\omega}} (a + a^\dagger)$

$|\psi(0)\rangle = \frac{1}{\sqrt{2}} |\varphi_0\rangle + \frac{1}{\sqrt{2}} e^{i\theta_1} |\varphi_1\rangle$

$\langle X \rangle = \langle \psi(0) | X | \psi(0) \rangle$

$= \left(\frac{1}{\sqrt{2}} \langle \varphi_0 | + \frac{1}{\sqrt{2}} e^{-i\theta_1} \langle \varphi_1 | \right) \sqrt{\frac{\hbar}{2m\omega}} (a + a^\dagger) \left(\frac{1}{\sqrt{2}} |\varphi_0\rangle + \frac{1}{\sqrt{2}} e^{i\theta_1} |\varphi_1\rangle \right)$

$$a|0\rangle = 0; a|1\rangle = |0\rangle$$

$$a^+|0\rangle = |1\rangle; a^+|1\rangle = \sqrt{2}|2\rangle$$

$$\text{soit } (a+a^+) \left(\frac{1}{\sqrt{2}}|0\rangle + \frac{1}{\sqrt{2}}e^{i\Theta}|1\rangle \right) = \frac{1}{\sqrt{2}}e^{i\Theta}|0\rangle + \frac{1}{\sqrt{2}}|1\rangle + \frac{1}{\sqrt{2}}e^{i\Theta}|2\rangle$$

$$\text{soit } \langle x \rangle = \sqrt{\frac{\hbar}{2m\omega}} \left(\frac{1}{\sqrt{2}}\langle 0| + \frac{1}{\sqrt{2}}e^{-i\Theta}\langle 1| \right) \left(\frac{1}{\sqrt{2}}e^{i\Theta}|0\rangle + \frac{1}{\sqrt{2}}|1\rangle + e^{i\Theta}|2\rangle \right)$$

$$= \sqrt{\frac{\hbar}{2m\omega}} \left(\frac{1}{2}e^{i\Theta} + \frac{1}{2}e^{-i\Theta} \right) = \sqrt{\frac{\hbar}{2m\omega}} \cos\Theta = \frac{1}{\sqrt{2}} \sqrt{\frac{\hbar}{2m\omega}}$$

$$5) |\psi(t)\rangle = \frac{1}{\sqrt{2}} e^{-i\omega t/2} |0\rangle + \frac{1}{\sqrt{2}} e^{i\pi/4} e^{-3i\omega t/2} |1\rangle$$

soit $\cos\Theta = \frac{\sqrt{2}}{2} \Rightarrow \Theta = \frac{\pi}{4}$

$$\text{soit } \Theta_1(t) = \frac{\pi}{4} - \frac{3\omega t}{2} - \frac{1}{2}\omega t = \frac{\pi}{4} - \omega t$$

$$\Rightarrow \langle x \rangle(t) = \sqrt{\frac{\hbar}{2m\omega}} \cos(\omega t - \pi/4)$$

Partie B] $e^{R S} = e^{R+S} e^{\frac{1}{2}[R,S]}$

$$1) D(k) = e^{\alpha a^+ - \alpha^* a} \Rightarrow D^+(k) = e^{\alpha^* a - \alpha a^+}$$

$$D^+(k) D(k) = D(k) D^+(k) = 1 \rightarrow \text{opérateur unitaire.}$$

$$2) D(k)|0\rangle \quad R = \alpha a^+ \text{ et } S = -\alpha^* a$$

$$\Rightarrow [R, S] = [\alpha a^+, -\alpha^* a] = -|\alpha|^2 \cos[\alpha a^+] = 1$$

$$D(k)|0\rangle = e^{\alpha a^+ - \alpha^* a} |0\rangle = e^{-|\alpha|^2/2} e^{\alpha a^+} e^{-\alpha^* a} |0\rangle$$

$$\text{calcul de } e^{-\alpha^* a} |0\rangle = |0\rangle - \alpha^* |1\rangle + \frac{\alpha^{*2}}{2} |2\rangle + \dots$$

$$\text{Reimpléti } e^{\alpha a^+} (e^{-\alpha^* a} |0\rangle) = e^{\alpha a^+} |0\rangle = \sum_m \frac{(\alpha a^+)^m}{m!} |0\rangle$$

$$\text{avec } (a^+)^m |0\rangle = \sqrt{m!} |m\rangle$$

$$\text{Finalement } D(k)|0\rangle = e^{-\frac{|\alpha|^2}{2}} \sum_m \alpha^m \frac{\sqrt{m!}}{m!} |m\rangle = \sum_m \frac{e^{-\frac{|\alpha|^2}{2}}}{\sqrt{m!}} \alpha^m |m\rangle = |\alpha\rangle_{\text{c.g.f.d.}}$$

3) Calcul $[a, a^{+2}] = [a, a^+ a^+] = a a^+ a^+ - a^+ a^+ a = (a a^+ a^+ - a^+ a^+ a) = 2 [a, a^+] a^+$ ③

$$[a, a^{+m}] = m [a, a^+] a^{+(m-1)} \text{ admis}$$

calcul $[a, a^{+(m+1)}] = [a, a^+ a^{+m}] = a a^+ a^{+m} - a^+ a^{+m} a = (a a^+ a^{+m} - a^+ a^{+m} a) = [a, a^+] a^{+m} + a^+ [a, a^{+m}] = [a, a^+] a^{+m} + a^+ m [a, a^+] a^{+(m-1)} = (m+1) [a, a^+] a^{+m}$ *démontre à l'étape m+1*

on considère $F(a^+) = \sum_m C_m a^{+m}$

calcul $[a, F(a^+)] = \sum_m C_m [a, a^{+m}] = \sum_m C_m m [a, a^+] a^{+(m-1)} = \sum_m C_m m a^{+(m-1)}$

et $\frac{dF(a^+)}{da^+} = \frac{d}{da^+} \sum_m C_m a^{+m} = \sum_m C_m m a^{+(m-1)}$ $\Rightarrow [a, F(a^+)] = \frac{dF(a^+)}{da^+}$

Reprise des calculs avec $G(a) = \sum_m B_m a^m$, $[a^+, a^m] = m [a^+, a] a^{m-1}$

calcul $[a^+, G(a)] = \sum_m B_m [a^+, a^m] = \sum_m B_m m a^{m-1}$ $\Rightarrow [a^+, G(a)] = -\frac{dG(a)}{da}$

et $\frac{dG(a)}{da} = \sum_m B_m m a^{m-1}$

Comparaison $[a, D(k)] / [a, F(a^+)] \Rightarrow [a, D(k)] = [a, F(a^+)] = k D(k)$

Calcul $D^{-1}(k) a D(k)$: $[a, D(k)] = a D(k) - D(k) a \Leftrightarrow a D(k) = [a, D(k)] + D(k) a$
 $D^{-1}(k) (a D(k)) = D^{-1}(k) ([a, D(k)] + D(k) a)$

Calcul $D_{(k)}^{-1} a D_{(k)}$: $(D^{-1}(k) a D(k))^+ = k^* + a^+ = D^{-1}(k) a^+ D(k) = D^{-1}(k) a^+ D(k) = k^* + a^+$

4) Dem: $a D^{-1}(\alpha) |k\rangle = 0$

(4)

$$\begin{aligned} D^{-1}(\alpha) a D(\alpha) (D^{-1}(\alpha) |k\rangle) &= D^{-1}(\alpha) a |k\rangle = \alpha D^{-1}(\alpha) |k\rangle \\ &= (\alpha + a) D^{-1}(\alpha) |k\rangle = \alpha D^{-1}(\alpha) |k\rangle + a D^{-1}(\alpha) |k\rangle \end{aligned}$$

donc $a D^{-1}(\alpha) |k\rangle = 0$

$$D^{-1}(\alpha) |k\rangle = |k\rangle$$

et donc $D(\alpha) D^{-1}(\alpha) |k\rangle = |k\rangle = D(\alpha) |k\rangle$

qfd.

Opérateur d'évolution d'un spin 1/2

$$\vec{\Pi} = \gamma \vec{S}$$

$$\vec{B}_0 \begin{matrix} -\frac{\omega_x}{\gamma} \\ -\frac{\omega_y}{\gamma} \\ -\frac{\omega_z}{\gamma} \end{matrix}$$

1) $U(t) = e^{-\frac{iWt}{\hbar}}$

avec $W = -\vec{\Pi} \cdot \vec{B}_0 = -\gamma \vec{S} \cdot \vec{B}_0$

$$= -\gamma (S_x B_x + S_y B_y + S_z B_z)$$

$$= (\omega_x S_x + \omega_y S_y + \omega_z S_z)$$

soit $\Pi = \frac{1}{\hbar} (\omega_x S_x + \omega_y S_y + \omega_z S_z)$

$$\begin{aligned} \Pi &= \frac{1}{2} [\omega_x \nabla_x + \omega_y \nabla_y + \omega_z \nabla_z] = \frac{1}{2} \left[\begin{pmatrix} 0 & \omega_x \\ \omega_x & 0 \end{pmatrix} + \begin{pmatrix} 0 & -i\omega_y \\ i\omega_y & 0 \end{pmatrix} + \begin{pmatrix} \omega_z & 0 \\ 0 & -\omega_z \end{pmatrix} \right] \\ &= \frac{1}{2} \begin{pmatrix} \omega_z & \omega_x - i\omega_y \\ \omega_x + i\omega_y & -\omega_z \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \Pi^2 &= \frac{1}{4} \begin{pmatrix} \omega_z & \omega_x - i\omega_y \\ \omega_x + i\omega_y & -\omega_z \end{pmatrix} \begin{pmatrix} \omega_z & \omega_x - i\omega_y \\ \omega_x + i\omega_y & -\omega_z \end{pmatrix} = \frac{1}{4} \begin{pmatrix} \omega_z^2 + \omega_x^2 + \omega_y^2 & 0 \\ 0 & \omega_x^2 + \omega_y^2 + \omega_z^2 \end{pmatrix} \\ &= \frac{1}{4} (\omega_x^2 + \omega_y^2 + \omega_z^2) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \left(\frac{\omega_0}{2} \right)^2 \end{aligned}$$

$$2) U(t) = e^{-i\pi t} = \cos(\pi t) - i \sin(\pi t)$$

$$\cos(\pi t) = \sum_m \frac{(-1)^m (\pi t)^{2m}}{(2m)!} = \sum_m \frac{(-1)^m \left(\frac{\omega_0}{2}\right)^{2m} t^{2m}}{(2m)!} = \cos\left(\frac{\omega_0 t}{2}\right)$$

$$\begin{aligned} \pi \sin(\pi t) &= \pi \sum_m \frac{(-1)^m (\pi t)^{2m+1}}{(2m+1)!} = \sum_m \frac{(-1)^m (\pi t)^{2m+2}}{t(2m+1)!} = \sum_m \frac{(-1)^m (\pi t)^{2(m+1)}}{t(2m+1)!} \\ &= \sum_m \frac{(-1)^m t^{2(m+1)}}{t(2m+1)!} \left(\frac{\omega_0}{2}\right)^{2(m+1)} = \frac{\omega_0}{2} \sum_m \frac{(-1)^m \left(\frac{\omega_0 t}{2}\right)^{2m+1}}{(2m+1)!} = \frac{\omega_0}{2} \sin\left(\frac{\omega_0 t}{2}\right) \end{aligned}$$

donc $U(t) = \cos\left(\frac{\omega_0 t}{2}\right) - i \frac{\omega_0}{2\pi} \sin\left(\frac{\omega_0 t}{2}\right) = \cos\left(\frac{\omega_0 t}{2}\right) - i \frac{\omega_0 \pi}{2\pi^2} \sin\left(\frac{\omega_0 t}{2}\right)$
 $= \cos\left(\frac{\omega_0 t}{2}\right) - \frac{2i\pi}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right)$ cqfd.

Matrice U(t)

$$U(t) = \cos\left(\frac{\omega_0 t}{2}\right) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \frac{i}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right) \begin{pmatrix} \omega_3 & \omega_x - i\omega_y \\ \omega_x + i\omega_y & -\omega_3 \end{pmatrix}$$

$$U(t) = \begin{pmatrix} \cos\left(\frac{\omega_0 t}{2}\right) - \frac{i}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right) \omega_3 & -\frac{i}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right) (\omega_x - i\omega_y) \\ -\frac{i}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right) (\omega_x + i\omega_y) & \cos\left(\frac{\omega_0 t}{2}\right) + \frac{i}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right) \omega_3 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

3) $|\psi(0)\rangle = |+\rangle$; $|\psi(t)\rangle = U(t)|+\rangle = \alpha|+\rangle + \beta|-\rangle$

$$S_{++}(t) = |\langle +|\psi(t)\rangle|^2 = |\langle +|U(t)|+\rangle|^2$$
 cqfd.

calcul de $\langle +|U(t)|+\rangle = \begin{pmatrix} \cos\left(\frac{\omega_0 t}{2}\right) - \frac{i}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right) \omega_3 \\ -\frac{i}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right) (\omega_x + i\omega_y) \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$$\langle +|U(t)|+\rangle = \cos\left(\frac{\omega_0 t}{2}\right) - \frac{i}{\omega_0} \sin\left(\frac{\omega_0 t}{2}\right) \omega_3$$

$$\begin{aligned} \Rightarrow P_{++}(t) &= |\langle + | U(t) | + \rangle|^2 = \cos^2\left(\frac{\omega_0 t}{2}\right) + \sin^2\left(\frac{\omega_0 t}{2}\right) \left(\frac{\omega_3}{\omega_0}\right)^2 \\ &= \left(1 - \sin^2\left(\frac{\omega_0 t}{2}\right)\right) + \left(\frac{\omega_3}{\omega_0}\right)^2 \sin^2\left(\frac{\omega_0 t}{2}\right) \\ &= 1 - \frac{(\omega_x^2 + \omega_y^2)}{\omega_0^2} \sin^2\left(\frac{\omega_0 t}{2}\right) \end{aligned} \quad (6)$$

$$P_{\max} = 1 - \frac{(\omega_x^2 + \omega_y^2)}{\omega_0^2}$$